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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC). 3 + - $r(t)$ $e(t)$ ADC μP DAC $u(t)$ Plant ? ? $y(t)$ 4

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Figure 2: Discrete-time control system b) It is generally advisable to have the crossover frequency of the loop gain centered between the crossover frequencies of the disturbance and the noise, which is at approximately 8rad/s . Also, the control system should be at least one

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